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SKILL SHEET 6.2.1 – COMPLETE AN ASSIGNMENT WHILE			JPR 6.2 Level 2 Rope			
	SUSPENDED - SELF RESCUE	Re	scue -	Mandat	ory	
Date:	Student Name:			Student #:		
Directions	: Given the allotted equipment, you are to descend a fixed rope system with a minimun	n workin	g heigh	t of 20ft		
	obstacle during the descent, and work your way past the obstacle in order to continue y		-			
	any questions?			J		
Task	Total	Initia	l Test	Ret	test	
Number	Task	Yes	No	Yes	No	
1	Selects appropriate equipment to perform evolution.					
2	Properly dons an approved Class II or II/III combination harness					
2 3 4	Evaluates surroundings for potential hazards					
4	Attaches descent control device to rope and harness					
	Performs a system safety check of existing fixed rope system (visual, load test and					
5	audible).					
5 6 7	Descends rope is a controlled manner and engages obstruction					
7	Properly attaches rope grab device to rope and harness					
	Properly uses rope grab device to take load off of and reapply load to descent control					
8	device					
<u>8</u> 9	Removes descent control device from rope and places it on rope below obstruction					
10	Removes rope grab device from line.					
11	Switches over to descent in a controlled manner					
12	Continues descent to ground					
	Were all tasks completed in a SAFE manner? ("NO" indicates automatic failure)					
		!				
Pass/Fail (	Criteria: Any "No" constitutes a failure of the station.	Pass		Pass		
		Fail		Fail		
Evaluator (	Comments:					
E	valuator Signature (initial):			_		
				_		
Ev	valuator Signature (retest):					



Circuit Silect				
L SHEET 6.2.2 – HIGH ANGLE VICTIM LOWER AND LITTER	JPR 6		•	escue -
Student Name:			Student	t #:
: Move a victim in a high-angle environment, given a rope rescue system, a minimum ve	rtical tr	avel dis	tance of	20 ft.,
sfer devices, and specialized equipment necessary for the environment, so that risks to v	ictim a	nd resc	uers are	
undesirable victim movement within the transfer device is minimized, means of attachr	nent to	the rop	e syster	n is
d, the victim is removed from the hazard, selected specialized equipment facilitates effici	ient vict	tim mov	ement,	and
can be transported to the local EMS provider.				
Tools	Initia	l Test	Retest	
I ask	Yes	No	Yes	No
Rescue needs are assessed and communicated				
Properly chooses victim transfer device and any needed specialized equipment				
Selects and uses proper PPE				
Properly attaches victim transfer device to the rope rescue system				
Reduces hazards for rescuers and victims as much as possible				
A system safety check is performed (visual, load test and audible)				
appropriately using webbing/rope so as to minimize any movement during evacuation.				
Visting acceptable law and to refer in a controlled acceptable				
Victim successfully lowered to safety in a controlled manner				
NAVene ell teche completed in a CAFF manuage 2 ("NO") in disease automostic feilum				
were all tasks completed in a SAFE manner? ( NO Indicates automatic failure)				
Pritoria: Any "No" constitutes a failure of the station	Dacc		Dacc	
interia. Any no constitutes a failure of the station.				
Comments	ı alı		i aii	
Comments.				
valuator Signature (initial):				
	Student Name:  Move a victim in a high-angle environment, given a rope rescue system, a minimum ve sfer devices, and specialized equipment necessary for the environment, so that risks to undesirable victim movement within the transfer device is minimized, means of attached, the victim is removed from the hazard, selected specialized equipment facilitates efficience be transported to the local EMS provider.  Task  Rescue needs are assessed and communicated  Properly chooses victim transfer device and any needed specialized equipment Selects and uses proper PPE  Properly attaches victim transfer device to the rope rescue system  Reduces hazards for rescuers and victims as much as possible A system safety check is performed (visual, load test and audible)  Simulated patient (mannequin) is positioned in patient transfer device and secured appropriately using webbing/rope so as to minimize any movement during evacuation.  Victim successfully lowered to safety in a controlled manner  Were all tasks completed in a SAFE manner? ("NO" indicates automatic failure)  riteria: Any "No" constitutes a failure of the station.	Student Name:  Move a victim in a high-angle environment, given a rope rescue system, a minimum vertical trisfer devices, and specialized equipment necessary for the environment, so that risks to victim a undesirable victim movement within the transfer device is minimized, means of attachment to did, the victim is removed from the hazard, selected specialized equipment facilitates efficient victican be transported to the local EMS provider.  Task Initia Yes  Rescue needs are assessed and communicated  Properly chooses victim transfer device and any needed specialized equipment  Selects and uses proper PPE  Properly attaches victim transfer device to the rope rescue system  Reduces hazards for rescuers and victims as much as possible  A system safety check is performed (visual, load test and audible)  Simulated patient (mannequin) is positioned in patient transfer device and secured appropriately using webbing/rope so as to minimize any movement during evacuation.  Victim successfully lowered to safety in a controlled manner  Were all tasks completed in a SAFE manner? ("NO" indicates automatic failure)  Proservation in a state of the station.  Pass Fail	Student Name:    Move a victim in a high-angle environment, given a rope rescue system, a minimum vertical travel dis sfer devices, and specialized equipment necessary for the environment, so that risks to victim and resc undesirable victim movement within the transfer device is minimized, means of attachment to the rop can be transported to the local EMS provider.    Task	Student Name:  Move a victim in a high-angle environment, given a rope rescue system, a minimum vertical travel distance of sfer devices, and specialized equipment necessary for the environment, so that risks to victim and rescuers are undesirable victim movement within the transfer device is minimized, means of attachment to the rope system, the victim is removed from the hazard, selected specialized equipment facilitates efficient victim movement, can be transported to the local EMS provider.  Task  Initial Test  Rescue needs are assessed and communicated  Properly chooses victim transfer device and any needed specialized equipment  Selects and uses proper PPE  Properly attaches victim transfer device to the rope rescue system  Reduces hazards for rescuers and victims as much as possible  A system safety check is performed (visual, load test and audible)  Simulated patient (mannequin) is positioned in patient transfer device and secured appropriately using webbing/rope so as to minimize any movement during evacuation.  Victim successfully lowered to safety in a controlled manner  Were all tasks completed in a SAFE manner? ("NO" indicates automatic failure)  Pass  Pass  Fail  Pass  Pass  Fail  Fail  Comments:

Evaluator Signature (retest):



SKILL SHEET 6.2.3 – FUNCTION AS A LITTER TENDER		JPR 6	JPR 6.2 Level 2 Rope Rescue - Mandatory			
Date:		Student Name:				t #:
distance of attachmen	f 20 ft., litters, brid	er tender in a high angle environment, given a rope rescue system, a lles, and specialized equipment, so that risks to victim and rescuers a em is secure, and the terrain is negotiated while minimizing risks to e	re minim quipmen	ized, th t or pei	rsons.	s of
Task Number		Task	Initia Yes	l Test No	Re <sup>-</sup> Yes	test No
	Selects and uses	proper harness and PPE	103		1.03	110
2	Selects and uses	•	-			
<del>-</del> 3		s the life safety harness to the rope rescue system	-			
1 2 3 4 5		tter past obstacles or natural structural features				
5		er while suspended				
6	Evaluates surroundings for potential hazards					
		<u> </u>			1	
13	Were all tasks co	mpleted in a SAFE manner? ("NO" indicates automatic failure)				
Pass/Fail C	Criteria: Any "No"	constitutes a failure of the station.	Pass		Pass	
			Fail		Fail	
Evaluator (	Comments:					
E	valuator Signature	(initial):			_	
Ev	valuator Signature	(retest):				



	SKILL SHEET 6.2.4 – ONE PERSON PICK-OFF			evel 2 R Mandat	•
		110	scue -		•
Date:	Student Name:			Studen	t #:
Directions	: Direct the team in the removal of a victim suspended from rope or webbing in a high	angle er	vironm	ent, give	en a
	pended by a harness attached to anchored rope, devices for removal of the victim and	-			
	he ground or safe area, so that risks and injury are minimized, means of attachment to				
the victim	is removed to safety and transferred to EMS	·	•		
Task		Initia	al Test	Re	test
Number	Task	Yes	No	Yes	No
1	Selects and constructs a system for rapid removal of the victim				
	Manages the operation of the system				
3	Determines suspended victims condition				
2 3 4 5	Reduces hazards for rescuers and victim as much as possible				
5	Determines special equipment needed for victim rescue				
12	Were all tasks completed in a SAFE manner? ("NO" indicates automatic failure				
		•	•	•	•
Pass/Fail (	Criteria: Any "No" constitutes a failure of the station.	Pass		Pass	
		Fail		Fail	
Evaluator	Comments:				
E	valuator Signature (initial):			_	
E <sup>,</sup>	valuator Signature (retest):				



SKILL SHEET 6.2.5 – CONSTRUCT A HIGHLINE ROPE RESCUE
SYSTEM

JPR 6.2 Level 2 Rope Rescue - Mandatory

Date:	Student Name:	Student #:

**Directions:** Direct a team in the construction of a highline system, given rescue personnel life safety rope, rope rescue equipment, a minimum span of 20 ft, and suitable anchor system capable of supporting the load, so that personnel assignments are made and clearly communicated, the system constructed can accommodate the load, tension applied with in the system will not exceed that rated capacity of any of its component parts, a system safety check is performed, movement on the system is efficient, and loads can be held in place e or moved with minimal effort over the desired distance

Task	Task	Initial Test	nitial Test Retes		est
Number	TdSK	Yes	No	Yes	No
1	Is able to determine incident needs as related to highline construction				
2	Evaluates the incident site interference and set-up concerns				
3	Identifies obstacles or voids to be negotiated with the highline				
	Track line(s) is tensioned using a simple mechanical advantage system on near side				
	and is anchored appropriately (3:1 or 4:1 system). * Soft rope grab devices (prusiks)				
4	should be utilized to warn of system overload				
	Track line tension is appropriate for system and does not exceed acceptable safety				
	margins for rope and hardware (500# on dynamometer for unloaded systems or 10 %				
5	of sag per 100 foot span per 200# load).				
	Pulley/trolley system is placed on track line(s) and control lines are attached to the				
6	trolley system				
	Control lines are rigged to either simple mechanical advantage systems or a descent				
7	control devices as system warrants based on rescue objectives				
8	System safety check is performed (visual, load test and audible).				
	Simulated rescue load (mannequin) is appropriately packaged in a patient transfer				
	device so as to not aggravate any potential injuries, movement within the device is				
9	minimized, and victim has appropriate personal protective equipment for the situation				
	Simulated rescue load is attached to the system in a safe manner so that the load is				
10	secure				
	Team directs the movement of the simulated rescue load in a clear and concise				
11	manner				
	Rescue load is moved to a predetermined point in a safe manner and can be secured				
12	at any point during the movement				
13	Were all tasks completed in a SAFE manner? ("NO" indicates automatic failure)	_			

Pass/Fail Criteria: Any "No" constitutes a failure of the station.		Pass	
	Fail	Fail	
Evaluator Comments:			

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Evaluator Signature (initial):	
Evaluator Signature (retest):	



SKILL S	SHEET 6.2.6 -	- DIRECT THE OPERATION OF A HIGHLINE ROPE			evel 2 R	•	
		RESCUE SYSTEM	KE	escue -	Mandat	ory	
Date:		Student Name:			Studen	t #:	
		the operation of a highline system, given rescue personnel, an estab	-				
•		oved and PPE, so that the movement is controlled, the load is held in	•			_	
	-	stem to the point of failure, personnel assignments are made and ta ified, communicated, and managed	sks are c	ommu	iicateu, a	mu	
Task	problems are identified, communicated, and managed				Test Rete		
Number		Task	Yes	No	Yes	No	
	Determines incid	ent needs					
1 2 3 4 5 6	Completes a syst	em safety check					
3		components for compromised integrity					
4	Selects and assign	ns personnel					
5	Communicates et	fectively					
6	Effectively manag	ges movement of the load					
7	Evaluates for any potential problems						
13	Were all tasks co	mpleted in a SAFE manner? ("NO" indicates automatic failure)					
Pass/Fail C	Criteria: Any "No"	constitutes a failure of the station.	Pass		Pass		
			Fail		Fail		
Evaluator (	Comments:						
Ev	valuator Signature	(initial):					
	variation dignature				_		
F۱	valuator Signature	(retest):					